FARO[®] Focus Laser Scanner

The most compact lightweight and intuitive laser scanner product line





ACCURACY

The Focus^s captures environments with increased accuracy and distance with dual-axis compensator and angular measurement.

ON-SITE COMPENSATION

With the on-site compensation functionality users can verify and adjust the Focus^s compensation on-site, ensuring high quality scan data.

ACCESSORY BAY

The accessory bay allows users to connect additional 3D laser scanning accessories to support a variety of projects.

TEMPERATURE

Extended temperature range allows scanning in challenging environments. The Focus can operate in temperatures as low as -20°C and up to 55°C.

IP RATING - CLASS 54

With the sealed design and certified with the industry standard Ingress Protection (IP) Rating, IP54, the Focus can be used in high particulate and wet weather conditions.

COMPACT AND PORTABLE

The Focus Laser Scanners measure at $230 \times 183 \times 103$ mm and weigh at 4.2kg making them the smallest and most light weight scanners in the market. The devices are equipped with a waterproof transport and ergonomic carrying case for maximum portability.

LASER SCANNERS FOR SHORT, MEDIUM AND LONG RANGE APPLICATIONS

FARO Focus Laser Scanners are specifically designed for both indoor and outdoor measurements in industries such as Architecture, Engineering, Construction, Public Safety and Forensics or Product Design. All devices capture real world information into the digital world to deliver information used to analyze, collaborate and execute better decisions to improve and maintain the overall project and product quality. All Focus^S and Focus^M scanners are equipped with recognizable features, such as Ingress Protection (IP) Rating, extended temperature range, HDR functionality, all in an ultra portable size.

The Laser Scanner Focus^S Series offers more advanced functionality in addition. Besides an increased distance and angular accuracy all Focus^S scanners are equipped with an internal accessory bay and an on-site compensation function quality verification. When utilized with SCENE Software, the Focus^S supports real time, on-site registration which enables 3D scan data to be wirelessly transmitted, processed, aligned and registered directly to an on-site mobile device/PC in real time.

BENEFITS

- Confidence and documented data quality by traceable vendor calibration and market leading on-site compensation.
- Scan in challenging environments while providing protection from dust, debris and water splashes.
- The Focus Laser Scanner portfolio offers the most economic 3D scanning solution for all requirements and budgets.
- Minimum training effort is ensured by the intuitive and easy to operate touch-screen interface as well as hands-on online tutorials.
- Efficient integration into existing software infrastructures and workflows are ensured by interfaces into various standard CAD systems.

FARO

PERFORMANCE SPECIFICATIONS

	FOCUS ^S SERIES S 350 S 150 S 70				FOCUS ^M					FOCUS ^S SERIES S 350 S 150 S 70	FOCUS ^M	
RANGING UNIT									INTEGRATED SENSORS			
Unambiguity interval:	614m for 122 to 488kpts/s				not specified				Dual axis compensator:	Performs a leveling of each scan with an accuracy of 19 arcsec valid within ±2°		
RANGE ¹ :	307m	for 976	6 kpts/s	S					Height sensor:	Via an electronic barometer the height relative to a fixed point can be		
00% reflectivity 0.6-350m 0.6-150m 0.6-70m 0.6 - 70m						· 70m				detected and added to a scan.		
(white) 10% reflectivity	0.6-150)m 0.6-'	150m 0	6-70m	0.6 - 70m				Compass ⁸ :	The electronic compass gives the scan an orientation.		
(dark-gray)	0.0 100	5111 0.0	10011110	.0 70111	0.0 - 7011				GNSS:	Integrated GPS & GLONASS		
2% reflectivity (black)	0.6- 50	m 0.6- {	50m 0.6	8-50m	0.6 - 50m				On-site compensation	Creates a current quality report and provides the		
RANGING NOISE ²	@10m	@10m noise reduc- tion ²	@25m	@25m noise reduc- tion ²	@10m	@10m noise reduc- tion ²	@25m	@25m noise reduc- tion ²		option to improve the devices compensa- tion automatically.	-	
				in ı	nm				Accessory bay	The accessory bay is lo-		
90% reflectivity (white) 10% reflectivity	0.30	0.15	0.30	0.15	0.70	0.40	0.70	0.40		cated on top of the laser scanner and is used to connect versatile acces-	-	
(dark-gray)									Real-time, on-site	sories to the scanner. Connects to SCENE		
2% reflectivity (black)	1.30	0.65	2.00	1.00	1.50	0.80	2.10	1.10	registration in SCENE	via WLAN. Processing of scan data, registra-		
Measurement speed (pts/sec):	122,000 / 244,000 / 488,000 / 976,000				122,000 / 244,000 / 488,000					tion and creation of overview map in SCENE		
Ranging error ⁴	±1mm			.,	±3mm					in real-time.		
Angular accuracy ⁵	19 arcsec for vertical/ not specified horizontal angles						d		GENERAL SPECIFICATIONS			
3D position accuracy ⁶	10m:	2mm /	25m: 3	8.5mm	not sp	not specified			Power supply voltage:	19V (external supply), 14.4V (internal battery)		
COLOR UNIT									Power consumption:	15W idle, 25W scanning, 80W charging		
Resolution:	Up to 165 megapixel color								Battery service life:	4.5 hours		
High Dynamic Range (HDR):	Exposure Bracketing 2x, 3x, 5x						5x		Operating temperature:	-5 - 40°C		
Parallax: DEFLECTION UNIT	Minimized due to co-axial design						sign		Extended operating temperature ⁹ :	-20 - 55°C		
Field of view	300° / 360°								Storage temperature:	-10 - 60°C		
(vertical ⁷ /horizontal): Step size	0.009° (40,960 3D-pixel on 360°) / 0.009° (40,960							960	Ingress protection (IP) rating class:	IP54		
(vertical/horizontal):	3D-pixel on 360°)							,,000	Humidity Resistence:	Non-condensing		
Max. vertical	97Hz								Weight incl. battery:	4.2kg		
scan speed:									Size/Dimensions:	230 x 183 x 103mm		
LASER (OPTICAL TRANSMITTER)								Maintenance /	Annual			
Laser class:	Laser class 1								calibration:			
Wavelength: Beam divergence:	1550nm 0.3mrad (1/e)									1 For a Lambertian scatter	0 0	
Beam diameter at exit:	2.12mm (1/e)								CLASS 1 LASER PRODUCT	defined as a standard deviation of values about the best-fit plane for measurement speed of 122,000 points/sec. 3 A noise-reduction algorithm may be		
DATA HANDLING AND CONTROL								activated by averaging raw data. 4 Ranging error				
Data storage:									is defined as a systematic measurement error at around 10m and 25m. 5			
Scanner control:									On-site compensation required. 6 For distances larger 25m add 0.1mm/m of uncertainty. 7 $2x150^{\circ}$, homogenous point spacing is not guaranteed. 8 Ferromagnetic objects can disturb the earth magnetic field and lead to inaccurate			
INTERFACE CONNECTION								magnetic objects can disturb the earth magnetic field and lead to maccurate measurements. 9 Low temperature operation: scanner has to be powered on				
WLAN:	WLAN: 802.11n (150Mbit/s), as Access Point or client in existing networks								while internal temperature is at or above 15°C, high temperature operation: additional accessory required, further information on request All accuracy specifications are one sigma, after warm-up and within operating temperature			
										e noted. Subject to change		







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